

### Some Probability Rules

**The probability of complement of A**

$$P(A') = 1 - P(A)$$

**If A and B are independent events,**

$$P(A \cap B) = P(A)P(B)$$

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

**If A and B are mutually exclusive events,**

$$P(A \cap B) = 0 \text{ since } (A \cap B) = \emptyset$$

$$P(A \cup B) = P(A) + P(B)$$

**The conditional probability of A for given B is**

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

### Bayes' Rule

If the events  $B_1, B_2, \dots, B_k$  constitute a partition of the sample space  $S$  such that  $P(B_i) \neq 0$  for  $i = 1, 2, \dots, k$ , then for any event  $A$  in  $S$  such that  $P(A) \neq 0$ ,

$$P(B_r|A) = \frac{P(B_r \cap A)}{P(A)} = \frac{P(B_r)P(A|B_r)}{\sum_{i=1}^k P(B_i \cap A)}$$

where

$$\begin{aligned} P(A) &= \sum_{i=1}^k P(B_i \cap A) = P(B_1 \cap A) + P(B_2 \cap A) + \dots + P(B_k \cap A) \\ &= P(B_1)P(A|B_1) + P(B_2)P(A|B_2) + \dots + P(B_k)P(A|B_k) \end{aligned}$$

### Discrete Probability Distributions

The set of ordered pairs  $(x, f(x))$  is a **probability function, probability mass function, or probability distribution** of the discrete random variable  $X$  if, for each possible outcome  $x$ ,

1.  $f(x) \geq 0$
2.  $\sum_x f(x) = 1$
3.  $P(X = a) = f(a)$

The **cumulative distribution function**  $F(x)$  of a discrete random variable  $X$  with probability distribution  $f(x)$  is

$$F(a) = P(X \leq a) = \sum_{t \leq a} f(t) \text{ for } -\infty < a < \infty$$

### Mathematical Expectation

Let  $X$  be a discrete random variable with probability distribution  $f(x)$ . The expected value of the  $g(X)$  is

$$\mu_{g(x)} = E[g(x)] = \sum_x g(x)f(x)$$

Let  $X$  be a discrete random variable with probability distribution  $f(x)$ . The expected value of the  $X$  is

$$\mu = E[X] = \sum_x xf(x)$$

Let  $X$  be a discrete random variable with probability distribution  $f(x)$  and mean  $\mu$ . The variance of  $X$  is

$$\sigma^2 = E[X^2] - \mu^2$$

## Binomial Distribution

Probability of  $x$  successes in  $n$  trials with  $P(\text{Success})=p$

$$X \sim b(x; n, p), \quad P(X = x) = b(x; n, p) = \binom{n}{x} p^x q^{n-x} \text{ for } x = 0, 1, \dots, n$$

The mean and standard deviation of the binomial distribution  $b(x; n, p)$  are  $\mu = np$  and  $\sigma = \sqrt{npq}$

### Approximation of Binomial Distribution by a Poisson Distribution

if  $n$  is large and  $p$  is close to 0, the Poisson dist. can be used, with  $\mu = np$ , to approximate binomial dist.

## Hypergeometric Distribution

Probability of  $x$  successes in a random sample of size  $n$  selected from  $N$  items of which  $k$  are labeled success and  $N - k$  labeled failure, is

$$X \sim h(x; N, n, k), \quad P(X = x) = h(x; N, n, k) = \frac{\binom{k}{x} \binom{N-k}{n-x}}{\binom{N}{n}} \text{ for } \max\{0, n - (N - k)\} \leq x \leq \min\{n, k\}$$

### Approximation of Hypergeometric Distribution by a Binomial Distribution

if  $n$  is small compared to  $N$ , the nature of the  $N$  items changes very little in each draw. So a binomial distribution can be used to approximate the hypergeometric distribution when  $n$  is small compared to  $N$ . In fact, as a rule of thumb, the approximation is good when  $n/N \leq 0.05$ .

## Negative Binomial Distribution

Probability of the  $k^{\text{th}}$  success occurs at  $x^{\text{th}}$  trial is

$$X \sim b^*(x; k, p), \quad P(X = x) = b^*(x; k, p) = \binom{x-1}{k-1} p^k q^{x-k} \text{ for } x = k, k+1, k+2, \dots$$

## Geometric Distribution

Probability of the *first* success occurs at  $x^{\text{th}}$  trial is

$$X \sim g(x, p), \quad P(X = x) = g(x, p) = pq^{x-1} \text{ for } x = 1, 2, \dots$$

The mean and standard deviation of the geometric distribution  $g(x, p)$  are  $\mu = \frac{1}{p}$  and  $\sigma = \frac{\sqrt{1-p}}{p}$

## Poisson Distribution

The probability distribution of the Poisson random variable  $X$ , representing the number of outcomes occurring in a given time interval or specified region

$$X \sim p(x; \lambda), \quad P(X = x) = p(x; \lambda) = \frac{e^{-\lambda} \lambda^x}{x!} \text{ for } x = 0, 1, 2, \dots$$

where  $\lambda$  is the average number of outcomes per unit time, distance, area, or volume.

Both the mean and the variance of the Poisson distribution  $p(x; \lambda)$  are  $\lambda$ .

## Continuous Probability Distributions

The function  $f(x)$  is a **probability density function** (pdf) for the continuous random variable  $X$ , defined over the set of real numbers, if

4.  $f(x) \geq 0$
5.  $\int_{-\infty}^{\infty} f(x)dx = 1$
6.  $P(a < X < b) = \int_a^b f(x)dx$

The **cumulative distribution function**  $F(x)$  of a continuous rv  $X$  with probability density function  $f(x)$  is

$$F(x) = P(X \leq x) = \int_{-\infty}^x f(t)dt \text{ for } -\infty < x < \infty$$

## Mathematical Expectation

Let  $X$  be a continuous random variable with probability distribution  $f(x)$ .

The expected value of the  $g(X)$  is  $\mu_{g(x)} = E[g(x)] = \int_{-\infty}^{\infty} g(x)f(x)dx$

The expected value of the  $X$  is  $\mu = E[X] = \int_{-\infty}^{\infty} xf(x)dx$

The variance of  $X$  is  $\sigma^2 = E[X^2] - \mu^2$

## The Joint Density Function

- The function  $f(x, y)$  is a joint density function of the continuous random variables  $X$  and  $Y$  if

1.  $f(x, y) \geq 0$  for all  $(x, y)$
2.  $\iint_{-\infty}^{\infty} f(x, y)dA = 1$
3.  $P[(X, Y) \in R] = \iint_R f(x, y)dA$  for any region  $R$  in the  $xy$ -plane.

- The **marginal distributions** of  $X$  alone and of  $Y$  alone are

$$g(x) = \int_{-\infty}^{\infty} f(x, y)dy \text{ and } h(y) = \int_{-\infty}^{\infty} f(x, y)dx \text{ for the continuous case.}$$

- Let  $X$  and  $Y$  be two random variables, discrete or continuous. The **conditional distribution** of the random variable  $Y$  given that  $X = x$  is

$$f(x|y) = \frac{f(x, y)}{h(y)}, \quad g(x) > 0$$

- Similarly, the conditional distribution of  $X$  given that  $Y = y$  is

$$f(y|x) = \frac{f(x, y)}{g(x)}, \quad h(y) > 0$$

- The random variables  $X$  and  $Y$  are said to be **statistically independent** if and only if

$$f(x, y) = g(x)h(y) \text{ for all } (x, y) \text{ within their range.}$$

### Mathematical Expectation

Let  $X$  and  $Y$  be random variables with joint probability distribution  $f(x, y)$ .

- The mean, or expected value, of the random variable  $g(X, Y)$  is

$$\mu_{g(x,y)} = E[g(x,y)] = \iint_{-\infty}^{\infty} g(x,y)f(x,y)dA$$

- The covariance of  $X$  and  $Y$  is

$$\sigma_{xy} = E[XY] - \mu_x\mu_y$$

where  $\mu_x = E[X] = \int_{-\infty}^{\infty} xg(x)dx$  and  $\mu_y = E[Y] = \int_{-\infty}^{\infty} yh(y)dy$

- The correlation coefficient of  $X$  and  $Y$  is  $\rho_{xy} = \frac{\sigma_{xy}}{\sigma_x\sigma_y}$

### Uniform Distribution

- The density function of the continuous uniform random variable  $X$  on the interval  $[A, B]$  is

$$f(x; A, B) = \begin{cases} \frac{1}{B-A}, & A \leq x \leq B \\ 0, & \text{elsewhere} \end{cases}$$

- The mean and variance of the uniform distribution are

$$\mu = \frac{A+B}{2}, \text{ and } \sigma^2 = \frac{(B-A)^2}{12}$$

### Standard Normal distribution

we are able to transform all the observations of any normal random variable  $X$  into a new set of observations of a normal random variable  $Z$  with mean 0 and variance 1. This can be done by means of the transformation

$$Z = \frac{X - \mu}{\sigma}$$

$$\text{So, } P(x_1 < X < x_2) = P(z_1 < Z < z_2)$$

### Normal Approximation to Binomial Distribution

If  $X$  is a binomial random variable with mean  $\mu = np$  and variance  $\sigma = \sqrt{npq}$ , then the limiting form of the distribution of

$$Z = \frac{Y - np}{\sqrt{npq}}$$

as  $n \rightarrow \infty$ , is the standard normal distribution  $n(z; 0, 1)$ , where  $Y$  is the upper or lower real limit of  $X$ .

The approximation will be good if  $np$  and  $n(1-p)$  are greater than or equal to 5.

### Exponential Distribution

The continuous random variable  $X$  has an **exponential distribution**, with parameter  $\beta$ , if its density function is given by

$$f(x; \beta) = \begin{cases} \frac{1}{\beta} e^{-\frac{x}{\beta}}, & x > 0 \\ 0, & \text{elsewhere} \end{cases}$$

where  $\beta > 0$  and  $\beta$  denotes the average time.

The mean and standard deviation of the exponential distribution are  $\mu = \beta$  and  $\sigma = \beta$ .

## The Moment Generating Function

$$M_t(x) = E[e^{xt}] = \sum_{x_{-\infty}}^{x_{\infty}} e^{xt} f(x) \text{ for discrete random variables}$$

$$M_t(x) = E[e^{xt}] = \int_{-\infty}^{\infty} g(x)f(x)dx \text{ for continuous random variables}$$

$$n^{\text{th}} \text{ moment } \mu_n = E[X^n] = \left. \frac{d^n M_t(x)}{dt^n} \right|_{t=0}$$

## The Joint Probability Distribution Function

- The function  $f(x, y)$  is a joint Probability Distribution Function of the Discrete random variables  $X$  and  $Y$  if
  1.  $f(x, y) \geq 0$  for all  $(x, y)$
  2.  $\sum_x \sum_y f(x, y) = 1$
  3.  $P[(X, Y) \in R] = \sum_x \sum_y f(x, y)$  for any region  $R$  in the  $xy$ -plane.
- The **marginal distributions** of  $X$  alone and of  $Y$  alone are

$$g(x) = \sum_y f(x, y) \text{ and } h(y) = \sum_x f(x, y) \text{ for the discrete case.}$$

- Let  $X$  and  $Y$  be two random variables, discrete or continuous. The **conditional distribution** of the random variable  $Y$  given that  $X = x$  is

$$f(x|y) = \frac{f(x, y)}{h(y)}, \quad g(x) > 0$$

- Similarly, the conditional distribution of  $X$  given that  $Y = y$  is

$$f(y|x) = \frac{f(x, y)}{g(x)}, \quad h(y) > 0$$

- The random variables  $X$  and  $Y$  are said to be **statistically independent** if and only if
 
$$f(x, y) = g(x)h(y) \text{ for all } (x, y) \text{ within their range.}$$

### The Hypotheses Testing

- i. State the null and alternative hypotheses.
- ii. Set the critical region
- iii. Compute the test statistics
- iv. Draw scientific or engineering conclusions.

$H_0$	Value of Test Statistic	$H_1$	Critical Region
$\mu = \mu_0$	$z = \frac{\bar{x} - \mu_0}{\sigma/\sqrt{n}}; \sigma \text{ known}$	$\mu < \mu_0$ $\mu > \mu_0$ $\mu \neq \mu_0$	$z < -z_\alpha$ $z > z_\alpha$ $z < -z_{\alpha/2} \text{ or } z > z_{\alpha/2}$
$\mu = \mu_0$	$t = \frac{\bar{x} - \mu_0}{s/\sqrt{n}}; v = n - 1,$ $\sigma \text{ unknown}$	$\mu < \mu_0$ $\mu > \mu_0$ $\mu \neq \mu_0$	$t < -t_\alpha$ $t > t_\alpha$ $t < -t_{\alpha/2} \text{ or } t > t_{\alpha/2}$
$\mu_1 - \mu_2 = d_0$	$z = \frac{(\bar{x}_1 - \bar{x}_2) - d_0}{\sqrt{\sigma_1^2/n_1 + \sigma_2^2/n_2}};$ $\sigma_1 \text{ and } \sigma_2 \text{ known}$	$\mu_1 - \mu_2 < d_0$ $\mu_1 - \mu_2 > d_0$ $\mu_1 - \mu_2 \neq d_0$	$z < -z_\alpha$ $z > z_\alpha$ $z < -z_{\alpha/2} \text{ or } z > z_{\alpha/2}$
$\mu_1 - \mu_2 = d_0$	$t = \frac{(\bar{x}_1 - \bar{x}_2) - d_0}{s_p \sqrt{1/n_1 + 1/n_2}};$ $v = n_1 + n_2 - 2,$ $\sigma_1 = \sigma_2 \text{ but unknown,}$ $s_p^2 = \frac{(n_1 - 1)s_1^2 + (n_2 - 1)s_2^2}{n_1 + n_2 - 2}$	$\mu_1 - \mu_2 < d_0$ $\mu_1 - \mu_2 > d_0$ $\mu_1 - \mu_2 \neq d_0$	$t < -t_\alpha$ $t > t_\alpha$ $t < -t_{\alpha/2} \text{ or } t > t_{\alpha/2}$

where  $s_p^2$  is pooled variance.